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HA400 HA900 HA401 HA901





General Description

The HA series are digital PID controllers with a high speed sampling time of 25 ms (0.025 sec) with high-resolution thermocouple, RTD or current voltage input, supplied with parameters settable in 1/100 sec.

A difference between HA400/900 and HA401/901 is in the autotuning. If the process is less than 30 seconds to setpoint, the HA400/900 is best suited with factory default values pre-set for fast process.

Applications in RTP (Rapid Thermal Process), RTA (Rapid Thermal Anneal) and temperature control of semiconductor manufacturing can be controlled by the HA series. The high speed sampling function also makes it suitable for other applications requiring fast control such as pressure or flow rate.

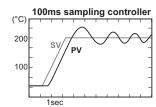


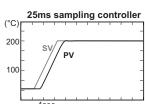
Features

- ☆ Ultra High Speed Sampling 0.025 sec
- ☆ Two Channels in One Controller
- ☆ Ramp / Soak Program Control
- ☆ Cascade Control
- ☆ Power Feed Forward Function
- ☆ Communications

Ultra High Speed Sampling 0.025 sec

The HA series digital controller supplies feedback control 40 times in one second. It makes the HA series suitable for any application requiring fast control response and high accuracy. The PID parameters can be set in 1/100 unit which supports extremely fast and accurate control by the HA series.

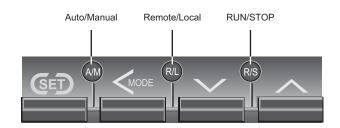




Direct Function keys

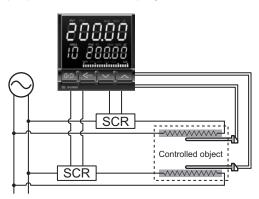
Direct function keys are marked for Auto/Manual, Remote /Local, and Run/Stop switching to eliminate error when entering changing patterns.

Used and Unused of each function key is also possible.



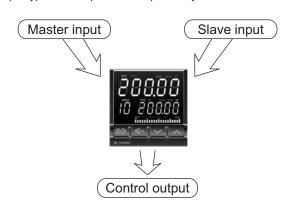
Two Channels in One Controller

Dual loop control can be performed with a single controller. All loops operate at 0.025ms sampling time.



Cascade Control in One Controller

Cascade control can be performed with a single controller. Input type can be specified independently for each channel.



High-Speed Digital Controller - 1 or 2 loops HA Series

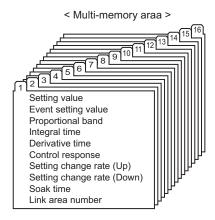


Features

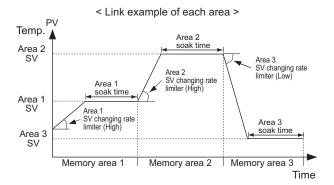
Ramp / Soak Program Control

The HA Series high speed temperature controller has Multimemory Area function which stores up to 16 sets of control parameters.

Parameters stored in each memory area are the control set value, event set value, PID values, control response, ramp-to-setpoint UP and DOWN, soak time, and link area number.



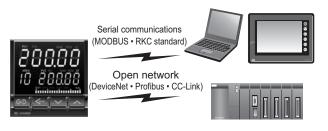
Up to 32-segment ramp/soak control is available by using the memory area function (ramp-to-set point UP and DOWN, soak time, link area number).



Communications

(Optional)

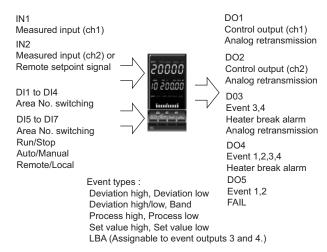
The HA Series incorporates a maximum of two communication ports. The communication method can be selected from serial communication (RS-485, RS-422A, RS-232C) and Open network (DeviceNet, Profibus, CC-Link).



Numerous Inputs and Outputs

A maximum of two measuring inputs (one input can be used as a remote setpoint signal) and seven event inputs can be specified. A maximum of five outputs can be specified, and various output functions (control output, analog retransmission, event up to 4) can be allocated in output logic operation.

• Available inputs and outputs depend on the specifications.



- · Sensor power supply output is also available.
 - 24V DC ± 5% (Max. 20mA)
 - Output from OUT3.
 - When sensor power supply output is specified, OUT4 and OUT5 can not be added.

Suitable for Various Process Control

Using industry standard DC inputs (current and voltage), the HA Series can be used in process control applications including pressure, flow rate and levels.

Autotuning

The Autotuning used on HA400/900 is suitable for a control system with a fast response. PID values can also be manually adjusted so that they may be further optimized for the processes.

Just for your information, this Autotuning is performs well for control systems in which temperature rises up to the set point in 30 seconds or faster. If the application is slower (e.g. 5 minutes to reach the set point), HA401/901 are recommended.

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High-Speed Digital Controller - 1 or 2 loops $HA\ Series$



Specifications

Input

Number of inputs

2 points (IN1 to IN2)

- · Isolated between each channel
- •2nd input (IN2) can be used as a remote input
- · Cascade connection available

Input

Universal input

a) Low voltage input group

: K, J, R, S, B, E, T, N (JIS/IEC) Thermocouple PLII (NBS), W5Re/W26Re (ASTM) •Influence of external resistance : Approx. $0.25\mu V/\Omega$ •Input break action : Up-scale / Down-scale (Selectable)

RTD: Pt100 (JIS/IEC), JPt100 (JIS)

•Influence of input lead resistance : Approx. 0.01[°C/Ω] of reading

•Maximum 10Ω per wire

•Input break action : Up-scale Low voltage : 0 to 1V DC, 0 to 100mV DC, 0 to 10mV DC •Input break action : Up-scale / Down-scale (Selectable)

Current: 4 to 20mA DC, 0 to 20mA DC

Input break action: Uncertain (indicates a value around 0mA)

b) High voltage input group

High voltage: 0 to 5V DC, 1 to 5V DC, 0 to 10V DC

•Input break action : Uncertain (indicates a value around 0V)

Sampling Time

0.025 sec

Input Digital Filter

0.01 to 10.00 sec (OFF when 0 is set.)

PV Ratio

0.500 to 1.500

Square Root Extraction

Equation : PV = √ (Input value x PV ratio + PV bias) Low level cut OFF: 0.00 to 25.00% of span

Performance

Measuring Accuracy

a) Thermocouple

Type: K, J, T, E, PLII

Less than -100°C (-148°F) : ±1.0°C (±1.8°F) -100 to 500°C (-148 to 932°F) : ±0.5°C (±0.9°F) More than 500°C (932°F) : ±(0.1% of Reading + 1 digit)

Type: N, S, R, W5Re/W26Re

Less than -100°C (-148°F): ±2.0°C (±3.6°F)

-100 to 1000°C (-148 to 1832°F) : ±1.0°C (±1.8°F) More than 1000°C (1832°F): ±(0.1% of Reading + 1 digit)

Less than 400°C (752°F): ±70.0°C (±126°F)

400 to 1000°C (752 to 1832°F): 1.0°C (1.8°F) More than 1000°C (1832°F): ±(0.1% of Reading + 1 digit)

Cold junction temperature compensation error

±1.0°C (1.8°F) [at 23°C±2°C (73.4°F± 3.6°F)

Within ±1.5°C (± 2.7°F) [Between 0 and 50°C (14 to 122°F)]

Less than 200°C (392°F): ±0.2°C (±0.4°F)

More than 200°C (392°F): ±(0.1% of Reading + 1 digit)

c) DC voltage and DC current

Insulation Resistance

More than $20M\Omega$ (500V DC) between measured terminals and ground More than $20M\Omega$ (500V DC) between power terminals and ground

1000V AC for one minute between measured terminals and ground 1500V AC for one minute between power terminals and ground

Control

- a) Brilliant PID control with enhanced autotuning.
- Available for reverse and direct action.
- b) Position proportioning control.
- ·a) or b) is selectable.

Major Setting Range

Derivative time:

Same as input range.

Proportional band: 0 to input span (Temperature input) 0.0 to 1000.0% of span (Voltage, Current

Integral time:

0.00 to 360.00sec. or 0.0 to 3600.0sec.

0.00 to 360.00sec. or 0.0 to 3600.0sec.

(selectable)

Slow, Medium, Fast -5.0 to +105.0% (High/Low individual setting) Control response: Output limiter Output change rate limiter :0.0 to 100.0%/sec. (Up/Down individual setting)

Proportional cycle time: 0.1 to 100.0 sec.

Memory area

Motor Valve Control (position proportioning control type only)

Input resistance (feedback resistance): 135Ω as standard

POS sampling cycle: 0.075 sec.

0.1 to 10.0% (output), resolution 0.1% Neutral zone :

Output: Relay output

Motor rotating speed: Suitable for ??? to ??? sec. (full open to full

· When motor valve control is used, neither heater break alarm nor

power feed forward function is available.

Output

Main Output

Number of output: Up to 3 points (OUT1 to OUT3) Output function: OUT1, 2: Control output

OUT3: Event output or analog retrans-

mission output (Optional)

Output type: Relay output :

Form A contact, 250V AC 3A (resistive load) Voltage pulse output : 0/12V DC (Load resistance : More than 600Ω) Current output: 4 to 20mA DC, 0 to 20mA DC

(Load resistance : Less than 600Ω) Continuous voltage output :

0 to 5V DC, 1 to 5V DC, 0 to 10V DC (Load resistance : More than $1k\Omega$) SSR (Triac) output (Rated current : 0.4A)

Sub Output (Optional)

Number of output : Up to 2 points (OUT4, OUT5) Output function: Event output (Optional)

Output type: Relay output

Form A contact, 250V AC 1A (resistive load)

Sensor Power Supply Output (Optional)

24V DC ± 5% (Max. 20mA) • Output from OUT3.

When sensor power supply output is specified,

OUT4 and OUT5 can not be added.

Event (Alarm) Output

(Optional)

Number of Event Outputs

Up to 4 points (Event 1 to 4)

Alarms

Type: Deviation High, Low, High/Low, Band,

Process High, Low Set value High, Low

Differential gap: 0 to input span

Heater Break Alarm (For single phase) CT type CTL-6-P-N(30A), CTL-12-S56-10L-N(100A)

Display range : 0.0 to 100.0A

± 5% of input value or ± 2A (whichever is larger) Accuracy:

Control Loop Break Alarm (LBA)

0.1 to 7200 sec. (OFF by setting zero) LBA time setting:

LBA deadband: 0 to input span

Assignable to main output (OUT3) or sub output (OUT4 to 5).

Other Functions

HOLD action (Valid for deviation/band/PV alarms only) Selection of event action for input abnormality.

High-Speed Digital Controller - 1 or 2 loops HA Series



Specifications

Non-isolated Remote Setpoint Input (Optional)

• Only available in a 1 channel control type.

Input

a) 0 to 1V DC, 0 to 100mV DC, 0 to 10mV DC b) 0 to 5V DC, 1 to 5V DC, 0 to 10V DC c) 4 to 20mA DC, 0 to 20mA DC

Accuracy

0.1% of span

Event Input

(Optional)

Number of Inputs

Up to 7 points

Input Rating

Non-voltage contact input

Functions

- a) Memory area selection
- b) Run/Stop switching
- c) Remote/Local switching
- d) Auto/Manual switching

· Event input logic selection functional allocation table

	DI1	DI2	DI3	DI4	DI5	DI6	DI7
1	Me		rea sele to 16)	ection	Area set	Run/Stop	Auto/Manual
2	Me	,	rea sele to 16)	ection	Area set	Run/Stop	Remote/Local
3	Ме	,	rea sele to 16)	ection	Area set	Remote/Local	Auto/Manual
4	Memory	y area s (1 to 8)	election	Area set	Run/Stop	Remote/Local	Auto/Manual
5	Memory area selection (1 to 8)				Remote/Local		
6	Memor	y area s (1 to 8)	election	Area set	Auto/Manual		

Analog Retransmission Output (Optional)

Number of Outputs

Up to 3 points

Functions are assignable to OUT1 to OUT3.

Output types

- a) Measured value (PV)
- b) Deviation (DV)
- Set value (SV)
- d) Manipulated output value (MV)

Communications

(Optional)

Number of communications: 2 points

Communication method: COM1: RS-485, RS-232C

COM2: RS-232C, RS-485, RS-422A

DeviceNet, PROFIBUS, CC-Link

Communication speed: 2400, 9600, 19200, 38400 BPS

Protocol: ANSI X3.28(1976) 2.5 A4

MODBUS

Bit format

Start bit :

 For MODBUS 8 bit only Data bit : 7 or 8

Parity bit: Without, Odd or Even

Stop bit:

Communication code: ASCII(JIS) 7-bit code RS-485, RS-422A: 31 Maximum connection:

(Address can be set from 0 to 99.)

Waterproof/Dustproof

(Optional)

Waterproof/dustproof protection: IP65

Waterproof/dustproof protection only effective from the front in panel mounted installations

General Specifications

Supply Voltage

HA900:

a) 90 to 264V AC (Including supply voltage variation)
[Rating : 100 to 240V AC] (50/60Hz common) b) 21.6 to 26.4V AC (Including supply voltage variation)

[Rating: 24V AC] (50/60Hz common)

c) 21.6 to 26.4V DC (Ripple rate 10% p-p or less) [Rating:24VDC]

Power Consumption

HA400: Less than 22.5VA for AC type (at 240V AC)

Less than 15.0VA for 24V AC type

Less than 430mA for 24V DC type Less than 24.0VA for AC type (at 240V AC)

Less than 16.0VA for 24V AC type Less than 470mA for 24V DC type

Power Failure Effect

Not affected by power failure shorter than 20msec, otherwise reset to the initial state. (HOT or COLD start is selectable.)

Self-Diagnostic Function

CPU power check, Adjustment data check, EEPROM check, RAM

Operating Environments: -10 to 50°C [14 to 122°F]

5 to 95% RH.

Absolute humidity: MAX. W.C 29g/m3 dry

air at 101.3kPa.

Memory Backup: Backed up by non-volatile memory

Number of writing: Approx. 100,000 times

Net Weight

HA400 Approx. 360g HA900: Approx. 460g External Dimensions (W x H x D) 48 x 96 x 100mm 96 x 96 x 100mm

Compliance with Standards

 UL Recognized CSA Certified C-Tick Mark







Event output logic selection functional allocation table

_		tput logic con	odion fanotion	ai ailooation te	
	OUT1	OUT2	OUT3	OUT4	OUT5
1	output	HBA1 (Energized) HBA2 (Energized)	Event3 (Energized) Event4 (Energized)	Event2 (Energized)	Event1 (Energized)
2	CH1 control output	HBA1 (De-energized) HBA2 (De-energized)	Event3 (De-energized) Event4 (De-energized)	Event2 (De-energized)	Event1 (De-energized)
3	CH1 control output	Event3 (Energized) Event4 (Energized) HBA1 (Energized) HBA2 (Energized)	Event2 (Energized)	Event1 (Energized)	FAIL (De-energized)
4	CH1 control output	Event3 (De-nergized) Event4 (De-nergized) HBA1 (De-energized) HBA2 (De-energized)	Event2 (De-energized)	Event1 (De-energized)	FAIL (De-energized)
5	CH1 control output	CH2 control output	Event4 (Energized) HBA2 (Energized)	Event3 (Energized) HBA1 (Energized)	Event1 (Energized) Event2 (Energized)
6	CH1 control output	CH2 control output		Event3 (De-energized) HBA1 (De-energized)	Event1 (De-energized) Event2 (De-energized)
7	CH1 control output	CH2 control output	Event3 (Energized) Event4 (Energized) HBA1 (Energized) HBA2 (Energized)	Event2 (Energized)	Event1 (Energized)
8	CH1 control output	CH2 control output	Event3 (De-nergized) Event4 (De-nergized) HBA1 (De-energized) HBA2 (De-energized)	Event2 (De-energized)	Event1 (De-energized)
10	CH1 control output (OPEN)	CH1 control output (CLOSE)	Event3 (Energized) Event4 (Energized) HBA1 (Energized) HBA2 (Energized)	Event2 (Energized)	Event1 (Energized)
11	output (OPEN)	CH1 control output (CLOSE)	HBA2 (De-energized)	Event2 (De-energized)	Event1 (De-energized)
12	output	TIDAZ (Ellergized)	TIDAT (Effetgized)	Event2 (Energized)	Event1 (Energized)
* Aı	n output logic	becomes OR output	t when two or more o	utput functions are as	signed to one output

When three analog outputs are selected, tha analog outputs are automatically assigned to

OUT1 through OUT3 and it has priority over the output logic selection

High-Speed Digital Controller - 1 or 2 loops $HA\ Series$



Model and Suffix Code

1 channel control type

Specifications	1/4 400 /40 - 00 1/2 7/1	Model and Suffix C	ode										
Model	HA400 (48 x 96mm 1/8 DIN size) HA900 (96 x 96mm 1/4 DIN size) HA401 (48 x 96mm 1/8 DIN size) HA901 (96 x 96mm 1/4 DIN size)		·	-□*							-□/	′□/	′⊏
Input (IN1 : No 1 input) Non isolated type remote set value	See Input and Range code table Not supplied See Remote input code table	0											_
Output 1 (Main output)	Relay contact output Voltage pulse output : 0/12V DC DC voltage : 0 to 5V DC voltage : 0 to 10V DC voltage : 1 to 5V DC current : 0 to 20mA DC current : 4 to 20mA SSR (Triac) output		M V 4 5 6 7 8										
1 3 Output 2 (Main output) * Not isolated from OUT1.	No output from OUT2 Relay contact output Voltage pulse output : 0/12V DC DC voltage : 0 to 5V DC voltage : 0 to 10V DC voltage : 1 to 5V DC current : 0 to 20mA DC current : 4 to 20mA SSR (Triac) output		N W 4 5 6 7 8 T										
Power supply	24V AC/DC 100 to 240V AC			3 4									
2 3 Output 3 (Main output)	No output from OUT3												
Output 4, 5 2 (OUT4, 5 : Sub output)	No outputs from OUT4 and OUT5 OUT4 : Relay contact output, No output f OUT4 and OUT5 : Relay contact output	from OUT5				N 1 2	N.						
Event input 1 to 5	Not supplied Event input : 5 points (DI 1 to DI5)						N 1						
CT input, Power feed forward (PFF) input, Feedback resistance	Not supplied CT input 1 point (CTL-6-P-N) CT input 1 point (CTL-12-S56-10L-N) CT input 2 points (CTL-6-P-N) CT input 2 points (CTL-12-S56-10L-N) PFF input (Within transformer 100 to 120V A PFF input (Within transformer 200 to 240V A CT input 1 point (CTL-6-P-N) + PFF input CT input 1 point (CTL-6-P-N) + PFF input CT input 1 point (CTL-12-S56-10L-N) + PF CT input 1 point (CTL-12-S56-10L-N) + PF Feedback resistance input	AC type) (Within transformer 100 to (Within transformer 200 to F input (Within transform	o 240\ ner 100	AC to 12	ype) 20V <i>A</i>	AC ty	ype) ype)	NPSTU123456F					
Communication 1 or Event input 6 to 7	Not supplied RS-232C (ANSI/RKC standard) RS-485 (ANSI/RKC standard) RS-485 (MODBUS) RS-232C (MODBUS) Event input: DI6 and DI7								N 1 5 6 8 D				
Communication 2	Not supplied RS-232C (ANSI/RKC standard) RS-422A (ANSI/RKC standard) RS-485 (ANSI/RKC standard) RS-485 (MODBUS) RS-422A (MODBUS) RS-232C (MODBUS) DeviceNet PROFIBUS CC-Link									N 1 4 5 6 7 8 A B C			
	Not supplied									i	N		_
Waterproof/Dustproof	Waterproof/Dustproof protection White										1	N	

¹ Only OUT1 can be used for control outputs. (Only OUT1 and OUT2 can be used for position proportioning control.)

Caution

- If two isolated analog outputs are required, use OUT1 (or OUT2) and OUT3. OUT1 and OUT2 are not isolated.
- To use as a position proportioning controller, two or more outputs must be supplied.
- If heater break alarm is assigned to event function, current transformer (sold separately) is required.

Autotuning

The Autotuning used on HA400/900 is suitable for a control system with a fast response. PID values can also be manually adjusted so that they may be further optimized for the processes.

Just for your information, this Autotuning is performs well for control systems in which temperature rises up to the set point in 30 seconds or faster. If the application is slower (e.g. 5 minutes to reach the set point), HA401/901 are recommended.

² Event (alarm) outputs, heater break alarm outputs are assignable to OUT3 - OUT5.

3 Analog output (PV, SV, etc) are assignable to OUT1 - OUT3.

High-Speed Digital Controller - 1 or 2 loops HA Series



Model and Suffix Code

2 channel control type

Specifications		Model and Suffix Co	nde										
Ореспісацогіз	HA400 (48 x 96mm 1/8 DIN size)	Woder and Guilly Ge	,ac										
Model	HA900 (96 x 96mm 1/4 DIN size) HA401 (48 x 96mm 1/8 DIN size) HA901 (96 x 96mm 1/4 DIN size)] 🗆	-□*			-□				-0/	′□/	
Input 1 (IN1 : No 1 input) Input 2 (IN2 : No 2 input)	See Input and Range code table See Input and Range code table												
1 3 Output 1 (Main output)	Relay contact output Voltage pulse output: 0/12V DC DC voltage: 0 to 5V DC voltage: 0 to 10V DC voltage: 1 to 5V DC current: 0 to 20mA DC current: 4 to 20mA SSR (Triac) output	N 4 5 6 7 8 7											
1 3 Output 2 (Main output) * Not isolated from OUT1.	No output from OUT2 Relay contact output Voltage pulse output: 0/12V DC DC voltage: 0 to 5V DC voltage: 0 to 10V DC voltage: 1 to 5V DC current: 0 to 20mA DC current: 4 to 20mA SSR (Triac) output		NMV 45678T										
Power supply	24V AC/DC 100 to 240V AC			3 4									
2 3 Output 3 (Main output)	No output from OUT3 Relay contact output Voltage pulse output: 0/12V DC DC voltage: 0 to 5V DC voltage: 0 to 10V DC voltage: 1 to 5V DC current: 0 to 20mA DC current: 4 to 20mA SSR (Triac) output Sensor power supply output (Output 4 a	nd 5 can not added)			N M V 4 5 6 7 8 T P								
Output 4, 5 2 (OUT4, 5 : Sub output)	OUT4 : Relay contact output, No output OUT4 and OUT5 : Relay contact output	No outputs from OUT4 and OUT5 OUT4 : Relay contact output, No output from OUT5 1 OUT4 and OUT5 : Relay contact output 2											
Event input 1 to 5	Not supplied Event input : 5 points (DI 1 to DI5)						N 1						
CT input, Power feed forward (PFF) input, Feedback resistance	Not supplied CT input 1 point (CTL-6-P-N) CT input 1 point (CTL-12-S56-10L-N) CT input 2 points (CTL-6-P-N) CT input 2 points (CTL-12-S56-10L-N) PFF input (Within transformer 100 to 120V PFF input (Within transformer 200 to 240V CT input 1 point (CTL-6-P-N) + PFF input CT input 1 point (CTL-6-P-N) + PFF input CT input 1 point (CTL-12-S56-10L-N) + PFF Feedback resistance input	AC type) t (Within transformer 100 to t (Within transformer 200 to FF input (Within transform	240\ er 100	/ AC ty) to 12	/pe) 0V A	C ty C ty	rpe)	NPSTU123456F					
Communication 1 or Event input 6 to 7	Not supplied RS-232C (ANSI/RKC standard) RS-485 (ANSI/RKC standard) RS-485 (MODBUS) RS-232C (MODBUS) Event input : DI6 and DI7								N 1 5 6 8 D				
Communication 2	Not supplied RS-232C (ANSI/RKC standard) RS-422A (ANSI/RKC standard) RS-485 (ANSI/RKC standard) RS-485 (MODBUS) RS-422A (MODBUS) RS-232C (MODBUS) DeviceNet PROFIBUS CC-Link									N 1 4 5 6 7 8 A B C			
Waterproof/Dustproof	Not supplied Waterproof/Dustproof protection White										N 1	N	
Body color	Black											A	·
Instrument version	Version symbol												Υ

- If two isolated analog outputs are required, use OUT1 (or OUT2) and OUT3. OUT1 and OUT2 are not isolated.
 To use as a position proportioning controller, two or more outputs must be supplied.
 If heater break alarm is assigned to event function, current transformer (sold separately) is required.

Autotuning
The Autotuning used on HA400/900 is suitable for a control system with a fast response. PID values can also be manually adjusted so that they may be further optimized for the processes.

Just for your information, this Autotuning is performs well for control systems in which temperature rises up to the set point in 30 seconds or faster. If the application is slower (e.g. 5 minutes to reach the set point), HA401/901 are recommended.

 $^{^1}$ Only OUT1 and OUT2 can be used for control outputs. 2 Event (alarm) outputs, heater break alarm outputs are assignable to OUT3 - OUT5. 3 Analog output (PV, SV, etc) are assignable to OUT1 - OUT3.

High-Speed Digital Controller - 1 or 2 loops $HA\ Series$

Range and Input Table

Thermocouple, RTD, Low voltage and Current group

Input	Code	Rai	nge	Resolution
K	K	-200 - 1372°C	-328 - 2501°F	
J	J	-200 - 1200°C	-328 - 2192°F	
Т	Т	-200 - 400°C	-328 - 752°F	
E	Е	-200 - 1000°C	-328 - 1832°F	
PLII	Α	0 - 1390°C	32 - 2534°F	1°C, 0.1°C, 1°F, 0.1°F
N	N	0 - 1300°C	32 - 2372°F	(Selectable)
S	S	-50 - 1768°C	-58 - 3214°F	
R	R	-50 - 1768°C	-58 - 3214°F	
W5Re/W26Re	W	0 -2300°C	32 - 4172°F	
В	В	0 - 1800°C	32 - 3272°F	
Pt100 (3 wire)	D	-200 - 850°C	-328 - 1562°F	1°C, 0.1°C, 0.01°C
JPt100 (3 wire)	D	-200 - 600°C	-328 - 1112°F	1°F. 0.1°F. 0.01°F
Pt100 (4 wire)	С	-200 - 850°C	-328 - 1562°F	(Selectable)
JPt100 (4 wire)	J	-200 - 600°C	-328 - 1112°F	(Selectable)
0 - 10mV DC				
0-100mV DC	3	40000	00000	1 0 1 0 01 0 001 0 0001
0 - 1V DC		-19999 —	99999 mable)	1, 0.1, 0.01, 0.001, 0.0001
0 - 20mA DC	8	(Program	mable)	(Programmable)
4 - 20mA DC	٥			

Remote Signal Code Table

Not isolated from the No.1 input [IN1]

	Input type							
	0 - 10mV DC							
Low voltage group	0 - 100mV DC	G						
	0 - 1V DC							
	0 - 5V DC							
High voltage group	0 - 10V DC	V						
	1 - 5V DC							
Current group	0 - 20mA DC							
Current group	4 - 20mA DC	'						

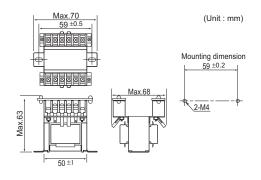
High voltage group

0 - 5V DC 0 - 10V DC 1 - 5V DC 6 (Programmable)	1, 0.1, 0.01, 0.001, 0.0001 (Programmable)
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Power Feedback Transformer (for Power Feed Forward Input)

- Supplied when power feed forward function is specified.
- When ordering transformer for replacement, please specify one of the following model codes :

Specification	Model Code
100 to 120V AC type	PFT - 01
200 to 240V AC type	PFT - 02

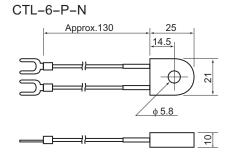


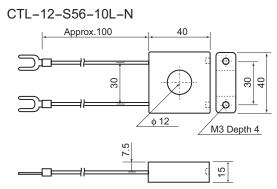
Current Transformer (CT) I

Sold separately.

Name	Range	Model Code					
Current transformer for	0 — 30A	CTL-6-P-N					
heater break alarm	0 -100A	CTL-12-S56-10L-N					

(Unit:mm)





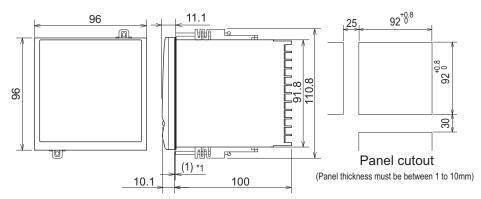


External Dimensions and Rear Terminals

Unit: mm

HA900, HA901

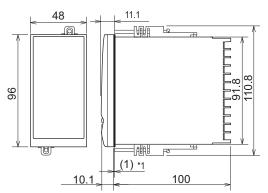
1		49	8	37	0	25	0	13	®
2	®	50	®	38	0	26	®	14	©
3	©	51	0	39	0	27	0	15	0
4		52	(3)	40	(D)	28	(3)	16	€
5	®	53	(3)	41	€	29	(3)	17	€
6	©	54	(3)	42	(3)	30	(3)	18	€
7	®	55	0	43	0	31	(3)	19	€
8	©	56	(3)	44	(3)	32	(3)	20	0
9	©	57	€	45	(D)	33	€	21	€
10	(1)	58	0	46	0	34	0	22	1
11	(D)	59	(3)	47	0	35	0	23	€
12	®	 80	(C)	48	®	36	(3)	24	€



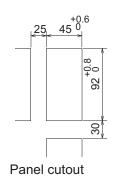
^{*1} IP65 waterproof/dustproof protection is molded into case and can not be added in the field.

HA400, HA401

1	0	25	0	13	0
2	0	26	(3)	14	0
3	(D)	27	0	15	0
4	0	28	0	16	0
5	0	29	0	17	0
6	0	30	(18	0
7	0	31	0	19	(3)
8	0	32	(20	0
9	(D)	33	0	21	0
10	(1)	34	(3)	22	0
11	(D)	35	0	23	0
12	0	36	0	24	0



*1 IP65 waterproof/dustproof protection is molded into case and can not be added in the field.



(Panel thickness must be between 1 to 10mm)

No	Descr	ription		No		No	Desci	ription	1	No	Description	
1	100 - 240V AC 24V DC 24V AC	Power supply	50	1		25 26	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	*		13 14	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	(1)RS-485 (2)RS-232C
3	No Relay contact	* Output 5 (OUT5)	5	39		27	T(B) (2) T/R (B) (3) RD	Communication (1) RS-422A		15		B) Event input 6 to 7 Non-voltage contact input
4	output	, , ,	5	40		28		(2) RS-485 (3) RS-232C	Ш	16	(0) '	A) CT1,CT2 input *
5	Relay contact	* Output 4 (OUT4)	5	41		29	(1) R(B)			17		B) Feedback resistance input
6	output	Catpat 1 (CC11)	54	42	Not used	30	(-)	*	11	18	CLOSE (C)	C) CT1 input + Power feed forward input
7		Output 3 (OUT3) * (1) Relay contact output (2) Voltage pulse/Current/	5	43		31				19	Non isolated type remote input (A) No.2 Input (IN 1) (B)	* A) 1 channel type
8	(1) (2) (3) (4)	Voltage output (3) SSR (Triac) output (4) Sensor power supply output	50	44		32	DI2 Non-voltage contact input	Event input 1 to 4		20		No.1 Input (IN1) + Non-isolated type
9	+	Output 2 (OUT2)*	5	45		33			Ш	21	No.1 Input (IN 1) (1) $B \rightarrow (2)$ (3) (3)	remote input 3) 2 channel type
10	(1) (2) - (3)	(2) Voltage pulse/Current/ Voltage output (3) SSR (Triac) output	5	46		34	DI4			22	No.1 Input (IN 1)	No.1 Input (IN1) + No.2 Input(IN 2)
11	+	Output 1 (OUT1)	5	47		35	COM (-) Non-voltage	*		23	-+ B\ -+ -+ B\ -+	(1) Thermocouple (2)-1 RTD (3 or 4 wire)
12	NO (1) (2) - (3)	Relay contact output Voltage pulse/Current/ Voltage output SSR (Triac) output	61	48		36	DI5 contact input	Event input 5		24	$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	(2)-1 RTD (3 or 4 Wire) (2)-2 RTD (3 wire) (3) Voltage/Current

^{*} Functions (A) to (C) and types (1) to (3) must be specified when instrument is ordered as change can not be made in the field.

^{* :} Option