# **DIGITAL INDICATING CONTROLLER LT470 SERIES**

LT470 series, 1/4 DIN size, new digital indicating controllers feature all functions including 5-digit display, newly developed PID algorithms and the Measured value (PV) new learning type overshoot suppression function (Parameter item in setting mode) JyroNavi which are convenient in various control applications.

■ MODEL (The figure of 1 in □ shows a standard specification.)

LT47	
	Input signal 0: Universal input
	0. Oniversal input
	Control output 1 (Heating)
	1: On-off pulse type 2: On-off servo type
	3: Current output type
	5: SSR drive pulse type
	6: Voltage output type
	U: Multiple control output type (On-off pulse type/current output
	type/SSR drive pulse type)
	Control output 2 (Cooling) (option)
	(This option cannot be applied to the Control output 1 of on-off servo type or multiple output type.)
	0: Not provided
	1: On-off pulse type 3: Current output type
	5: SSR drive pulse type
	6: Voltage output type
	Remote contacts input (standard)/
	Communications interface (option) 1: Remote contacts input 4 points (std)
	R: RS-232C (option)
	A: RS-422A (option)
	S: RS-485 (option) 0: Not provided (option)
	(The remote contacts input is equipped as standard when you select a communications interface.)
	Retransmission signal output
	1: 4 to 20mA (standard)
	2: 0 to 1V (option) 3: 0 to 10V (option)
	0: Not provided (option)
	Remote signal input (option) (This option is combined with the option of 2-point
	additional event. When you select the remote signal input, please specify the code of additional event as 1
	or 3.) 0: Not provided
	5: 4 to 20mA
	6: 0 to 1V 7: 0 to 10V
	Additional event (option)/CT (option) * 0: Not provided
	1: Event 2 points
	<ol><li>Heater disconnection (CT)</li></ol>
	3: Event 2-point + heater disconnection (CT)
	Water-proof
	0: Not provided 1: NEMA250 4X (IEC529 IP66)
L	Power voltage
	A: 100 to 240VAC (universal)
	ter disconnection (CT) is only applied to

the Control output 1 of on-off pulse type or SSR

drive pulse type.

Setpoint (SV), control output (OUT) or blank

[Parameter or data

in setting mode]

monitoring (operation mode)

DEV display	MODE DOWN UP SELVENT
	 Mode key Down key Up key Select∕ Entry key
Status disp	ay SV1 SV2 SV3 SV4 OUT MAN EV1 EV2
■ FEATURES	
<ul><li>Universal input</li><li>New PID algorithm</li></ul>	ting by 5-digit display ns built-in e overshoot suppression function
<ul> <li>MODBUS protoc system configuration</li> </ul>	col communications for easy ion
<ul> <li>Remote contacts are built-in as star</li> </ul>	input and retransmission output ndard.
<ul> <li>Various functions</li> <li>Only 7mm thickne</li> <li>Conformance to C</li> </ul>	•

(UL, CSA: Approval pending) Water-proof conforming to NEMA250

4X (equivalent to IEC529 IP66) (option)

### ■ MEASURING RANGES

I	nput type	Input range							
	В	0.0	to	1820.0°C	32	to	3300 °F		
	R	0.0	to	1760.0°C	32	to	3200 °F		
	S	0.0	to	1760.0°C	32	to	3200 °F		
	N	0.0	to	1300.0°C	32	to	2350 °F		
	к	-200.0	to	1370.0°C	-300	to	2450 °F		
	E	-200.0	to	700.0°C	-300.0	to	1250.0°F		
T/C	J	-200.0	to	900.0°C	-300.0	to	1650.0°F		
	Т	-200.0	to	400.0°C	-300.0	to	700.0°F		
	U	-200.0	to	400.0°C	-300.0	to	700.0°F		
	L -200.0		to	900.0°C	-300.0	to	1650.0°F		
	WRe5-WRe26	0	to	2310 °C	32	to	4190 °F		
	W-WRe26	0	to	2310 °C	32	to	4190 °F		
	PtRh40-PtRh20	0.0	to	1880.0°C	32	to	3400 °F		
	Platinel II	0.0	to	1390.0°C	32	to	2500 °F		
RTD	Pt100	-200.0	to	850.0°C	-300.0	to	1500.0°F		
RID	JPt100	-200.0	to	649.0°C	-300.0	to	1200.0°F		
	20mV	0 to 20mV (0.00 to 20.00)							
DC voltage	5V	0 to 5V	(0.000	to 5.000)	Scaling s				
	10V	0 to 10V	' (0.00	0 to 10.000)	Decimal	plac			
DC current				4 to 20mA (1.000 to 5.000 - Converted into voltage value)					

Note: For the current input, a  $250\Omega$  shunt resistor (sold separately) is required.





## SPECIFICATIONS

INPUT SPECIFICATIONS
Input signal:
Thermocouple B, R, S, N, K, E, J, T, U, L, WRe5-WRe26,
W-WRe26, PtRh40-PtRh20, Platinel II
Resistance thermometer Pt100, JPt100 DC voltage 0 to 20mV, 0 to 5V, 0 to 10V
DC current 4 to 20mA [By using a 250 $\Omega$ shunt resistor (sold
separately) and 5V range (1 to 5V)]
Measuring range:
Refer to the list of measuring ranges. Total of 20 kinds consisted of 14 kinds of thermocouple, 2 kinds of
resistance thermometer, 3 kinds of dc voltage, and 1 kind of dc current
Accuracy ratings:
±0.1% of measuring range ± 1 digit (at reference operation
conditions), exception PtRh40-PtRh20: $\pm 0.3\% \pm 1$ digit
Refer to the details of accuracy ratings. Reference junction compensation accuracy:
$\pm 1.0^{\circ}C$ (23°C $\pm$ 10°C), $\pm 2.0^{\circ}C$ (-10 to 50°C)
Temperature unit: °C or °F
Sampling period: Approx. 0.2 second
Burnout: Up scale/down scale (selectable)
Allowable signal source resistance: Thermocouple/mV input 250Ω or less
V input $1k\Omega$ or less
Resistance thermometer input $10\Omega$ or less (per wire)
Input resistance: Thermocouple/DC voltage 1MΩ or more
DC current Approx. 250Ω
<b>Measuring current:</b> Resistance thermometer 1mA ± 20%
Measuring input shift (sensor correction): Can be set with the resolution of 0.1 times the setting resolution
of SV (-19999 to 20000)
Digital filter: 0.0 to 99.9 seconds
Scaling: Range/scale of DC voltage/current input (-19999 to
20000), optional setting
Scale decimal point: 0 to 4
Maximum allowable input range: DC voltage±10VDC RTD±5VDC
Maximum common mode voltage: 30VAC
Common mode rejection ratio:
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<ul> <li>130dB or more (50/60Hz) (signal source resistance 1Ω or less)</li> <li>Series mode rejection ratio: 50dB or more (50/60Hz) (signal source resistance 1Ω or less)</li> <li>CONTROL SPECIFICATIONS</li> <li>Control cycle time: Approx. 0.2 second</li> <li>Control system: On-off pulse type PID system</li> <li>Current output type PID system</li> <li>SSR drive pulse type PID system</li> <li>On-off servo type PID system</li> <li>Voltage output type PID system</li> <li>Voltage output type PID system</li> <li>Yet pulse type PID system</li></ul>
130dB or more (50/60Hz) (signal source resistance 1Ω or less) Series mode rejection ratio: 50dB or more (50/60Hz) (signal source resistance 1Ω or less) CONTROL SPECIFICATIONS Control cycle time: Approx. 0.2 second Control system: On-off pulse type PID system Current output type PID system SSR drive pulse type PID system On-off servo type PID system Voltage output type PID system Multiple control type (on-off pulse type/current output type/SSR drive pulse type) PID system * 2-position control is selectable. Control setpoint: 4 sets switching, 5-digit setting Setpoint limiter: Within measuring range Setpoint ramp function: Setpoint ramp function: Setpoint rising ramp: 0 to 20000 (0 = no operation) Setpoint falling ramp: 0 to 20000 (0 = no operation) Setpoint falling ramp: 0 to 20000 (0 = no operation) PV start function At SV change, power-on, MAN to AUTO, etc. Control setpoint accuracy ratings: Relative error to displayed value $\pm 1$ digit Auto-tuning: Standard (Manual setting of PID constants enabled) PID constants: 4 sets switching (interlocking to SV) P 0.1 (0.0) to 999.9% (0 = 2-position) 1 0 to 9999 seconds D 0 to 9999 seconds PID deadband (gap): 0.0 to 9.9% (4 sets switching, interlocking to SV) Anti-reset windup: High limit 0.0 to 100.0%, Low limit100.0 to 0.0% Overshoot suppression function: On/off selectable (4 sets independent switching, interlocking to
<ul> <li>130dB or more (50/60Hz) (signal source resistance 1Ω or less)</li> <li>Series mode rejection ratio: 50dB or more (50/60Hz) (signal source resistance 1Ω or less)</li> <li>CONTROL SPECIFICATIONS</li> <li>Control cycle time: Approx. 0.2 second</li> <li>Control system: On-off pulse type PID system</li> <li>Current output type PID system</li> <li>SSR drive pulse type PID system</li> <li>On-off servo type PID system</li> <li>On-off servo type PID system</li> <li>Voltage output type PID system</li> <li>Yoltage output</li></ul>
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#### **Output specifications:**

On-off pulse type Output signal ... On-off pulse conductive signal Contact ratings ...

Resistive load 100VAC 5A, 240VAC 5A, 30VDC 5A 100VAC 2.5A, 240VAC 2.5A, 30VDC 2.5A Inductive load

Electrical relay life ... More than 100,000 times

Pulse cycle ... Approx. 1 second to 180 seconds adjustable

Contact protection element ... Not built-in [If required, add a contact protection element (sold separately) externally.] • Current output type

Output signal ... 4 to 20mADC, Load resistance ... 600Ω or less SSR drive pulse type

Output signal ... On-off pulse voltage signal

At ON 12VDC ± 20% (load current ... 20mA or less) At OFF 0.8VDC or less Pulse cycle ... Approx. 1 second to 180 seconds adjustable

- On-off servo type
- Output signal ... On-off conductive signal

Feedback resistance... 1000 to 2.5k0

Contact ratings ...

- Resistive load 100VAC 5A, 240VAC 5A, 30VDC 5A Inductive load 100VAC 2.5A, 240VAC 2.5A, 30VDC 2.5A Minimum load 5VDC or more, 10mADC or more
- Electrical relay life ... More than 100,000 times

Contact protection element ... Not built-in [If required, add a contact protection element (sold separately) externally.] Combination adjustment ... Manual or auto-tuning

Voltage output type

Output signal ... 0 to 10VDC

- Output resistance ... Approx.  $10\Omega$ Load resistance ...  $50k\Omega$  or more
- Output limiter: 4 sets switching (interlocking to SV)
- High limit ... 0.0 to 105.0%, Low limit ... -5.0 to 100.0%
- Output variation limiter: 4 sets switching (interlocking to SV) Rising ... 0.1 to 100.0%, Falling ... -100.0 to -0.1%
- Output preset: -100.0 to 100.0%
- **PV error output:** -5.0 to 105.0%
- Run/Ready: Run/ready (control stop, output: preset output value) selectable

Preset output: -5.0 to 105.0%

- Control at power recovery: Continuous/ready selectable Auto-output/man-output (AUTO/MANUAL): Balanceless bumpless switching

#### **EVENT SPECIFICATIONS**

Event point: 2 points (Additional 2 points can be added. - option) Event type:

- Setting to each of Event 1/2
- Absolute value alarm ... High/low, standby enabled/disabled Deviation alarm ... High/low, standby enabled/disabled Absolute value deviation alarm ... High/low, standby enabled/disabled
- Setpoint alarm ... High/low, standby enabled/disabled
- Output value alarm ... High/low, standby enabled/disabled
- Abnormal control loop, fail, heater disconnection alarm, timer function Event setpoint: Event 1/2, 4 sets individual setting
- Event deadband: Can be set by the resolution of 0.1 times the setting resolution of SV, Setting to each Event 1/2

#### Event delay: 0 to 9999 seconds

- Event output phase: Normal/reverse selectable
- Event output at Ready: Off/computation selectable
- Event output:
  - Output signal ... Form A relay output
  - Contact ratings ...
    - Resistive load 100VAC 3A, 240VAC 3A, 30VDC 3A
    - 100VAC 1.5A, 240VAC 1.5A, 30VDC 1.5A Inductive load Minimum load 5VDC or more, 10mADC or more
  - Electrical relay life ... More than 100,000 times
  - Contact protection element ... Not built-in [If required, add a contact protection element (sold separately) externally.]

#### **RETRANSMISSION OUTPUT SPECIFICATIONS**

Output signal being proportioned to the setpoint, the measured value, control output value, etc.

#### **Output signal:**

1 kind to be specified from 4 to 20mADC (load resistance ... 400 $\Omega$  or less), 0 to 1VDC, or 0 to 10VDC (output resistance ... approx.  $10\Omega$ , load resistance ...  $50k\Omega$  or more) Output accuracy: ±0.2% of retransmission scale range Output resolution: Approx. 1/30000 Retransmission scale: -19999 to 20000, optional setting



#### **REMOTE CONTACTS INPUT SPECIFICATIONS**

Following functions enabled by the remote contacts input

Input point: 4 points (No-voltage contacts or transistor open collector) (Remote contacts rating ...5VDC or more, 2mA or more)

#### Function:

- The following functions are allocated by parameter settings.
- (1) Setpoint external switching, (2) Auto/man external switching
   (3) Run/ready switching, (4) Timer start-up, (5) Holding of the setpoint ramp operation, (6) Resetting of the setpoint ramp operation,
- (7) Remote/local switching

#### **DISPLAY/SETTING SPECIFICATIONS**

Display type: 5-digit seven-segment LED display, two lines Status display ... 8 independent LEDs

Deviation display ... 2-segment

### **Display content:**

First LED (green) display ... At operation mode: Measured value (PV)

- Decimal place of PV is optionally set in 0 to 4.
- At setting mode: Parameter item
- Second LED (red) display ...

At operation mode: Setpoint (SV) or control output value (OUT) At setting mode: Parameter or data monitoring (operation mode) Status (red/green) ...

EV1 (red): Lights when EV1 is activated.

EV2 (red): Lights when EV2 is activated.

MAN (red): Lights when the control output value is set manually.

SV1/2/3/4 (green): The number selected is lit. OUT (green):Lights when the control output value is

displayed in the second display.  $\triangle$  or  $\nabla$  lights in accordance with Deviation display (green) ...

deviation (settable).

#### **Operation mode display:**

No display function of the operation mode screen, 5 levels Automatic return: Returns to operation mode if any key is not

pressed for more than 1 minute in setting mode.

Password: No display function of the setting mode screen by a password, 3 levels

Key lock: Locking function of parameters, 5 levels

Eng. port: Communications enabled by connecting the exclusive cable (Model: RZ-EC1) to the Eng. port at the upper side of the case. Parameter programming software package available (release shortly)

#### **GENERAL SPECIFICATIONS**

Rated power voltage: 100 to 240VAC 50/60Hz (universal) Allowable power voltage: 90 to 264VAC Power consumption: Approx. 16VA (max.)

Operation	Reference condition	Normal condition						
Ambient	23°C ± 2°C	-10 to 50°C						
temperature		(Max. 40°C for						
		closed-installation)						
Ambient humidity	55% ± 5%RH	20 to 90%RH						
Power supply	100VAC ± 1%	90V to 264VAC						
Power frequency	50Hz/60Hz ± 1%	50Hz/60Hz ± 2%						
Mounting angle	Forward/backward	Forward/backward						
	±3 degrees or less	±10 degrees or less						
Vibration/impact	$0 m/s^2 / 0 m/s^2$	$2m/s^2 / 0m/s^2$						

Ambient temperature change ratio: 10°C/H or less

Warm-up time: 30 minutes or more

Power interruption: Parameters are memorized by EEPROM (Writing: Approx. 100,000 times)

#### Insulation resistance:

Between primary side terminals (\*1) and secondary side terminals (\*2) 20M $\Omega$  or more at 500VDC

**Dielectric strength:** 

Between primary side terminals (\*1) and secondary side terminals (\*2) 1 minute at 1500VAC

\*1 = Terminals of power supply, control output event relay output \*2 = Terminals except above

Front and case: Front ... Non-flammable ABS

Case ... Non-flammable polycarbonate resin

Color: Gray

Installation: Flush panel installation

Weight: Approx. 350 to 500g (max.)

Transportation/storage condition (with packing at shipment): Ambient temperature ... -20 to 60°C

Ambient humidity ... 5 to 95%RH (no dew condensation) Vibration ... 0 to 4.9m/s<sup>2</sup> (10 to 60Hz)

Impact ... 400m/s<sup>2</sup> or less

#### **INTERNATIONAL STANDARDS**

CE: EN61326+A1 \*, EN61010+A2

UL: UL3121-1 (approval pending)

CSA (C-UL): C22.2, No. 1010 (approval pending)

NEMA: NEMA250 4X (front panel: option) (equivalent to IEC529 IP66) Note: Not available in closed-installation

The display of the measured value and output may vary up to ±10% or ±2mV under the EMC test ambient

#### ACCURACY RATINGS

	Input	Accuracy ratings	Details
	В		Not specified for less than 400°C 400°C to 800°C: ±0.2% ± 1 digit
T/C	R	±0.1% ± 1 digit	0°C to 400°C: ±0.2% ± 1 digit
	S	exception:	0°C to 400°C: ±0.2% ± 1 digit
	N, K, E, J, T, U, L	±0.2% ± 1 digit	
	WRe5-WRe26	for -200°C to 0°C	
	W-WRe26		0°C to 400°C: ±0.4% ± 1 digit
	Platinel II		
	PtRh40-PtRh20	±0.3% ± 1 digit	0°C to 400°C: ±2% ± 1 digit 400°C to 800°C: ±1% ± 1 digit
RTD	Pt100	±0.1% ± 1 digit	
RID	JPt100	±0.1% ± 1 uigit	
DC voltage	mV, V	±0.1% ± 1 digit	
DC current	mA	±0.1% ± 1 digit	By using the shunt resistor specified for current input

#### OPTIONS

Option	Contents
Control output 2	Control calculation:
(Heating/	Matching computation/cooling proportion
cooling)	computation switching
ocomig)	Matching computation parameters
	Split direct 0.0 to 60.0%
	• Split reverse 40.0 to 100.0%
	Cooling proportion computation parameters
	Cooling proportional band coefficient
	0.00 to 10.00
	• Deadband50.0 to 50.0%
	Pulse cycle: 1 second to 180 seconds (cooling side)
Communications	The setpoint and the measured value can be
interface	transmitted to a master CPU, and the parameters can
(RS-232C,	be set by the master CPU.
RS-422A or	Protocol: MODBUS, RTU mode/Ascii mode switching,
RS-485)	and private protocol
	Address: 01 to 99
	Communications function: 1 kind to be specified from
	setpoint/data transmission, digital transmission, or
	digital remote
Remote signal	Remote input function
input	By the remote contacts, Remote or Local can be
	selected, and the setpoint can be set in Remote.
	This function can be used in a secondary controller
	for cascade control.
	Input signal:
	1 kind to be specified from 4 to 20mADC (input
	resistance approx. $50\Omega$ ), 0 to 1VDC (input
	resistance approx. $500k\Omega$ or more), or 0 to
	10VDC (input resistance approx. $100k\Omega$ or
	more)
	Input accuracy: $\pm 0.3\%$ of input range $\pm 1$ digit
	Input resolution: Approx. 1/40000
	Remote scale:
	Optional setting from –19999 to 20000
	Remote shift:
	Can be set by the resolution being 0.1 times the
	setting resolution of SV (-19999 to 20000)
	Cascade primary controller function
	Cascade calculation:
	$SV2 = (a + d \times SV1/100) \times MV1 + b + c \times SV1$
	SV2 SV (%) of secondary controller
	SV2 SV (%) of primary controller
	MV1 PID constants (%) of primary controller
	Cascade parameters:
	a = primary ratio fixed parameter 0.01 to 1.00
	b = primary bias fixed parameter
	-100.0 to 100.0%
	c = Primary bias variable parameter 0.00 to 100.0%
	d = Primary ratio variable parameter 0.00 to 1.00
Heater	
Heater	Function to detect the heater disconnection by CT
disconnection	input (CT: separate purchase required)
detection	Input signal: 5.0 to 50.0AAC (50/60Hz)
	Input accuracy: ±5% of full scale ± 1 digit
	Resolution: Approx. 1/400
	Recommended CT: Model CTL-6-S-H
Water-proof	For water-proofing of the front panel, a rubber packing
	is inserted between a controller and a panel board.
	NEMA250 4X (equivalent to IEC529, IP66)
	This option cannot be applied for closed-installation.



#### TERMINAL BOARD

A	В	С		Е	
	1	1	3)	<b>(4)</b>	51
	$\overline{2}$	$\[ \] \] \] \] \[ \] \] \] \[ \] \] \] \[ \] \] \[ \] \] \[ \] \] \[ \] \] \[ \] \] \] \[ \] \] \[ \] \] \[ \] \] \[ \] \] \[ \] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \] \[\] \[\] \] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[\] \[\] \[\] \] \[$	32	2	62
3	13	3	33	43	63
4	14	@	34	44	64
6	(15)	25	35	45	65
	16	@	66	46	66
$\bigcirc$	$\bigcirc$	1	3	47	57
8	18	28	38	48	58
9	19	29	39	49	69
	20	30	@	50	50

Note) 1. All terminal screws are M3.5. 2. For Y-tip or O-tip, use it with

or less.

the outside dimension of 7mm

Line A Measuring input/control output 1/power supply

лt	No.	Voltage (current *)	T/C	RTD
inpu	(1)	+		
uring	2		+	А
Measuring input	3	-	-	В
~	4			В

\* For current input

Con	Connect a shunt resistor (250Ω, sold separately) to + and – terminals.									
(Bu	No.	On-off pulse type multiple output 1 (On-off pulse output)	SSR drive pulse type Current output type Voltage output type	On-off servo type See Line C						
out 1 (heat	6	H (NC)	+							
Control output 1 (heating)	7	C (COM)	-							
0	8	L (NO)								
5	9	L (live)								

N (Neutral)

#### Line B Communications/remote contacts input

0	No.	RS-232C	RS-422A	RS-485
terface	(11)	SD	SDA	SA
ons int	(12)		SDB	SB
Communications interface	(13)	RD	RDA	
Domm	14		RDB	
)	(15)	SG	SG	SG
out	(16)	DI1+		
cts inp	17	DI2+		_
Remote contacts input		DI3+		-
note (	19	DI4+		_
Rer	20	DI-COM		

#### Line C Retransmission output/control output 2/CT/event output ... differs on output type of heating control.

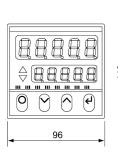
No.		Standard No. On-off servo type		No.	Mu	ultiple type	No				
21	+	Retransmission	21)			(21)	+	Retransmission	(21	) +	Retransmission output
22	-	output	22	R1 (open)		22	-	output	(22	) –	(On-off servo type only)
23	H (NC) +		23	RC (common)	100 to 2kΩ	23			23	) +	Remote input
24	C (COM)	Control output 2 (cooling)	24	R2 (close)		24	+	Multiple output 2	(24	) –	Remote input
25	L (NO)		25	M3 (close)		25	-	(SSR drive pulse)	(25	)	
26	СТ	CT input	26	M2 (open)		26	+	Multiple output 3	(26	) R/L+	Remote/Local
27)	СТ	CT input	27)	M1 (common)	Power	27)	-	(Current output)	(27	) R/L-COM	*
28	EV1	Buffer relay	28	EV1	Buffer relay	28	EV1	Buffer relay	(28	) EV3	- Buffer relay
29	EV2	Buffer relay	29	EV2	Buffer relay	29	EV2	— Buffer relay →	(29	) EV4	Buffer relay
30	COM12	Power	30	COM12 —	Power	30	COM12	- Power	(30	) COM34	Power
$\leq$			$\bigcirc$						$\sim$	) COM34	

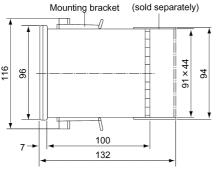
Note) The retransmission output is in Line E for on-off servo type and in Line C for other types.

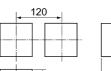
\* R/L: Analog remote/local switching (ON: Remote, OFF: Local)

Line E Remote contacts input, etc.

DIMENSIONS AND PANEL CUTOUT (Steel plate with thickness of 1 to 10mm is recommended for installation.) Terminal cover







92

+0.8

92

General installation

 Closed-installation panel dimension (Not applied to optional water-proof)



Unit:mm

### ACCESSORIES (Separate purchase is required.)

Accessory	Remarks
CT (current transformer)	Recommendation: Model CTL-6-S-H
Terminal cover	The depth is extended to 132mm by the terminal cover.
Shunt resistor for current input (250 $\Omega$ )	For measurement by DC current of 4 to 20mA

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Specifications subject to change without notice. Printed in Japan (I) 2002.1

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